

# Development of 3D printable materials for soft sensing in robotics **Diana Cafiso** Supervisor: Prof. Candido Fabrizio Pirri, dr. Lucia Beccai dr. Simone Lantean, dr. Ignazio Roppolo

### **Research context and motivation**

- Recently, soft robots are emerging due to their versatility. Advanced soft sensors are mandatory to endow them with touch and proprioception.
- Programming the structure and the morphology of the sensor is an appealing strategy to control its deformations in three dimensions and to enhance the sensing performances.
- Porosity can be exploited at two levels to program and tune the sensor mechanical properties: at material level by microporosity and at architecture level by 3D lattice design.
  - GOAL : development of 3D printable and conductive porous materials for soft sensors



### Addressed research questions/problems

Porosity

Photocurability

Electrical conductivity

Soft inks for VP-3D printing for soft sensors with programmable properties and morphologies



## Submitted and published works, Conferences

- Cafiso, D., Septevani, A.A., Noè, C., Schiller, T., Pirri, C., Roppolo, I., Chiappone, A. "3D printing of fully cellulose-based hydrogels by digital light processing", Sustainable Materials and Technologies, vol. 32, 2022
- Cafiso, D., Lantean, S., Joe, S., Beccai, L. "3D printing Approaches for Soft Robotics", AIV XXV conference, Napoli, 11/05/2022

- □ 01UIERP- Additive Manufacturing Processes for Polymeric Materials (attended)
- □ 01QKGRW Monitoraggio strutturale con la tecnica delle emissioni acustiche (attended)
- □ 01DTQRV The art of manipulation in robotics and metaverses (attended)







**PROBOSCIS** 



**Electrical, Electronics and** 

#### **Communications Engineering**